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Bayesian Source Identification with Dual Hierarchical Neural Networks for Urban Air Pollution

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Healthy People and Healthy Planet: AI for Decarbonized, Healthy, Inspiring, and Energy Positive Cities

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Introduction

- Air pollution is a growing concern with many negative impact on public health and the environment.
- Identifying the sources of pollution can help address air quality issues and inform policies and regulations for reducing harmful emissions.
- We propose a novel hierarchical framework for urban air pollution source identification, leveraging deep learning (DL) within an efficient Bayesian inference framework.



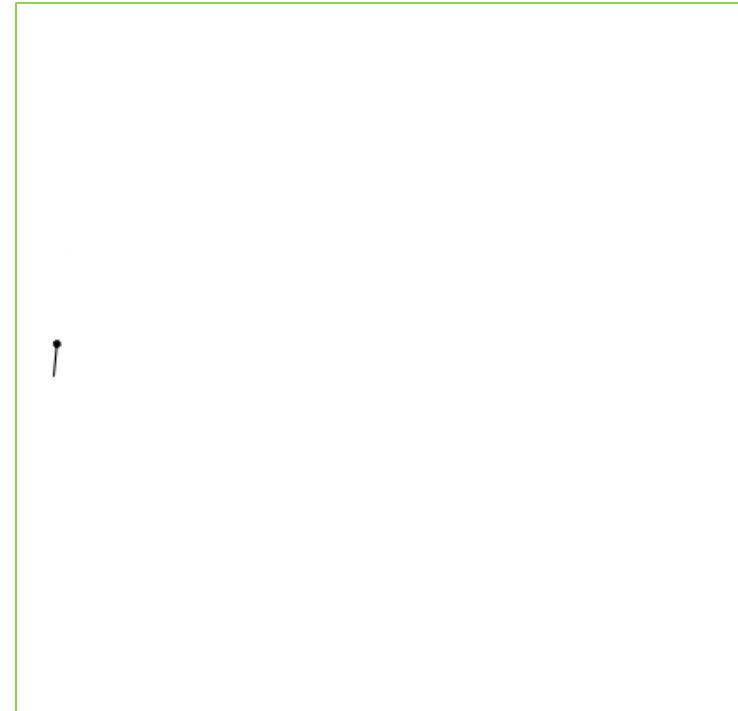
Bayesian Inference

- Baye's rule

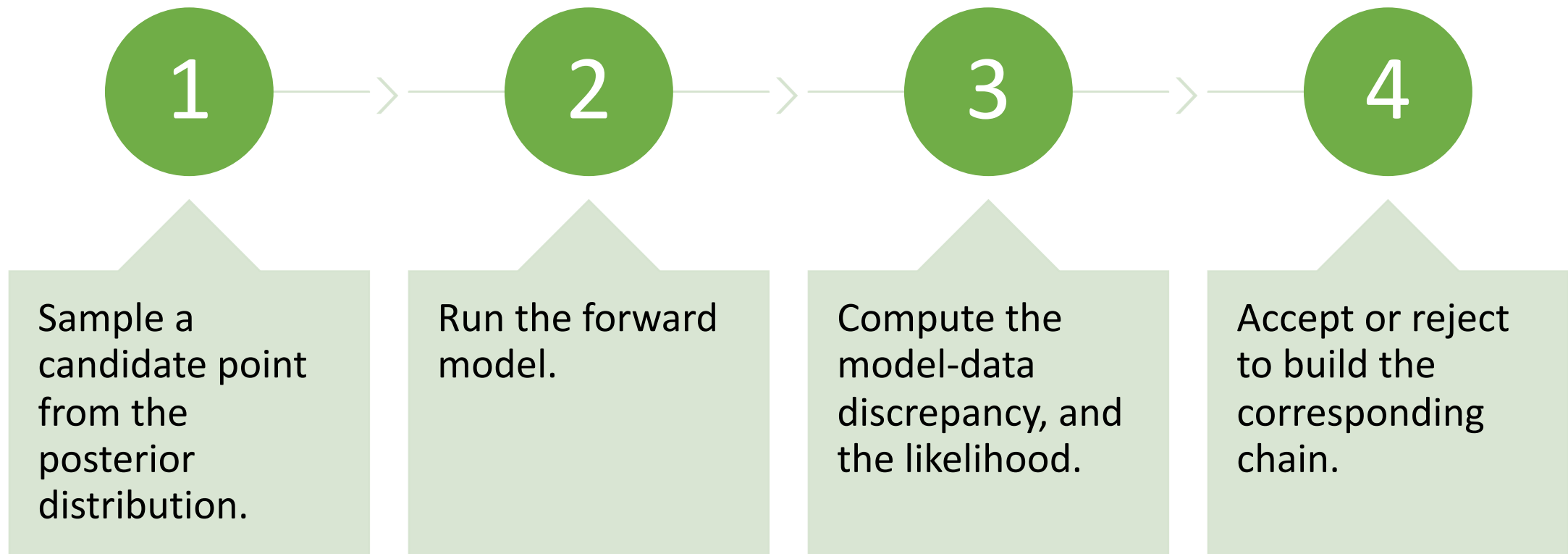
$$\pi(M|D) \propto \pi(M)\pi(D|M)$$

Posterior probability \propto prior probability \times likelihood probability

- Advantages:
 - Incorporating prior knowledge
 - Adapting to new information
 - Uncertainty quantification
- Requirement: stochastic sampling tools \rightarrow Monte Carlo Markov Chain (MCMC) family



Metropolis Hastings-MCMC Algorithm



MH-MCMC in Air Pollution Source Identification

Inverting for 4 parameters (M)

- Longitude (x)
- Latitude (y)
- Emission Rate (q)
- Emission Duration (d)

Uniform prior distribution $\pi(M)$

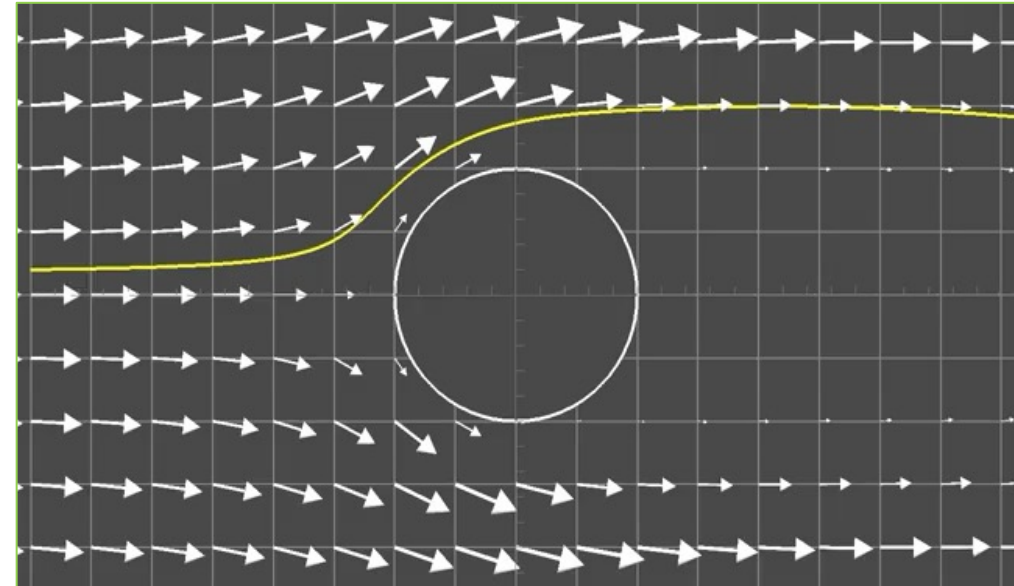
MH-MCMC in Air Pollution Source Identification

- Available environmental monitoring techniques:
 - Sensors
 - Satellite images
 - Remote sensing techniques
- Two forms of pollution observations:
 - Discrete point-wise concentration values
 - Concentration fields

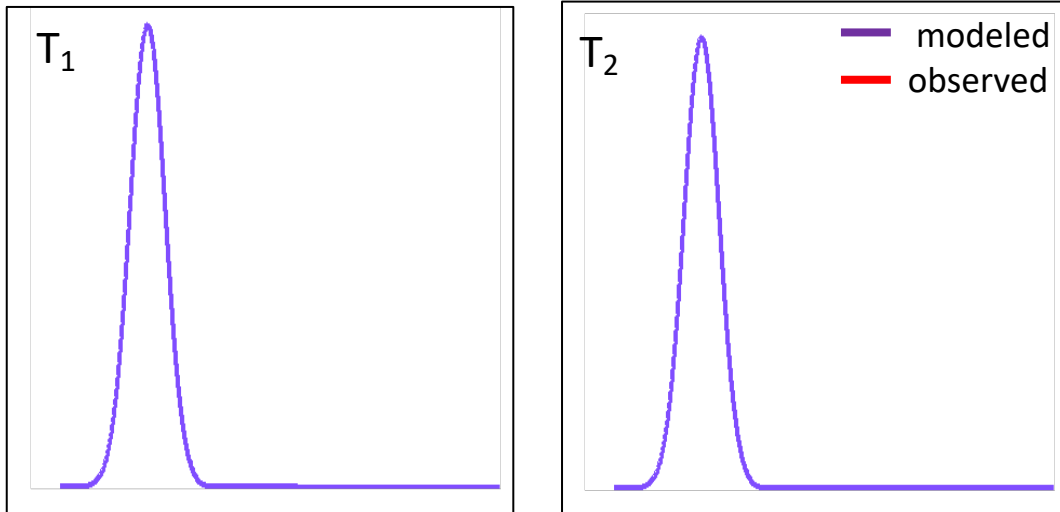


The Lagrangian Transport Model

- The Graz Lagrangian model **GRAL**:
 - Microscale wind field computations.
 - Lagrangian particle tracking.
- Navier-Stokes equation along with the k- ϵ turbulence closure model.
- Inputs: topography, land use, buildings, meteorological conditions and emission sources.

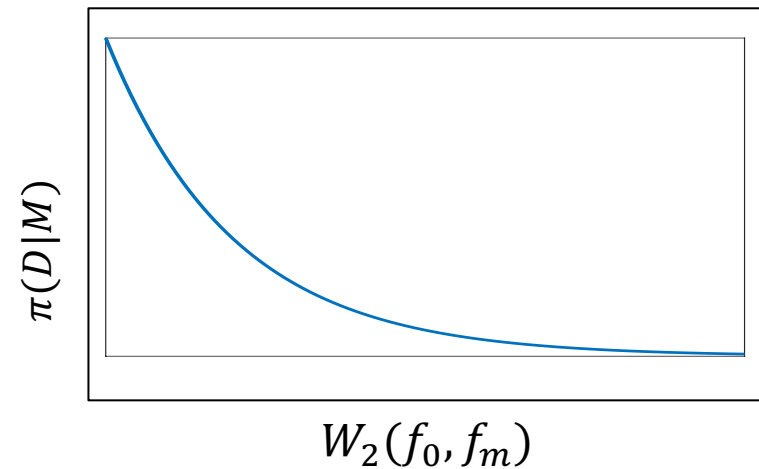


Modeling the Likelihood



- Each concentration field is considered as a distribution that could be displaced.
- The Wasserstein distance is the cost of displacing the predicted model output to the observation.
- This cost physically represents the required work as the product of the mass to be moved and the distance to be traveled.

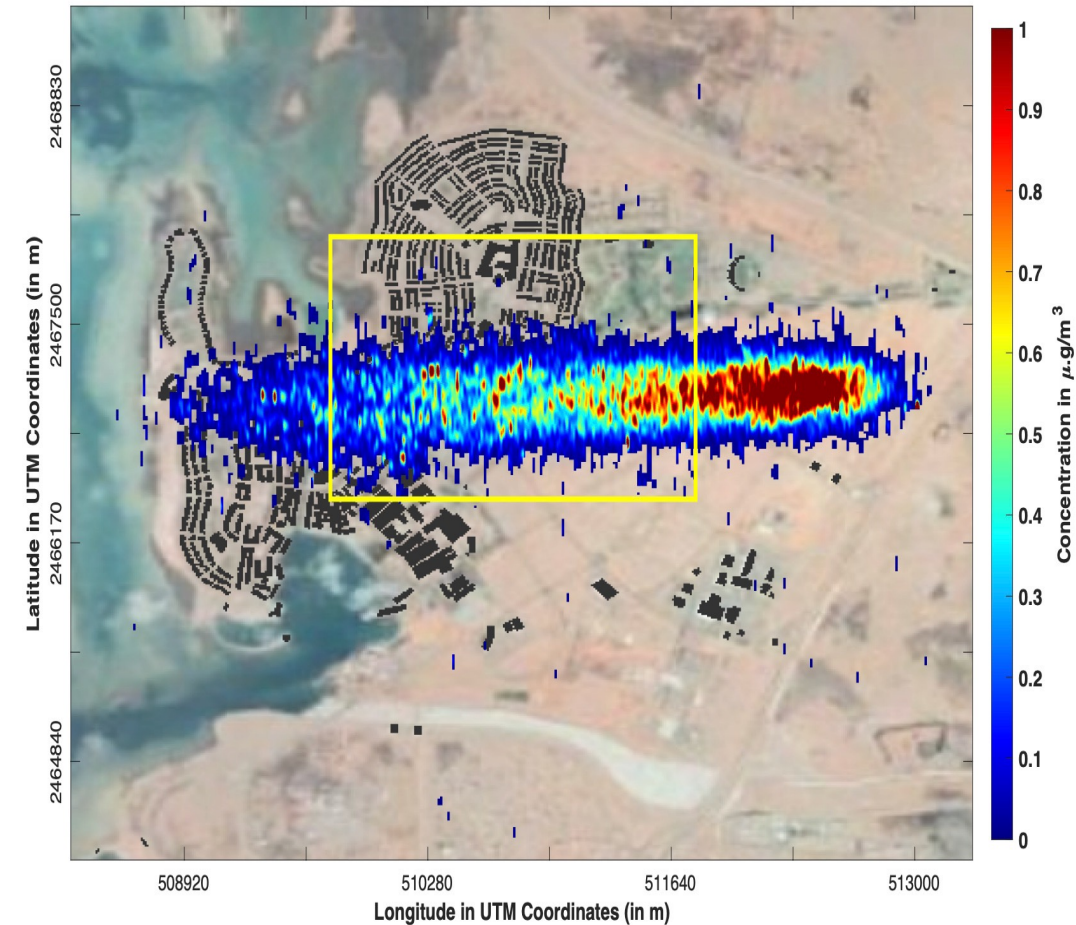
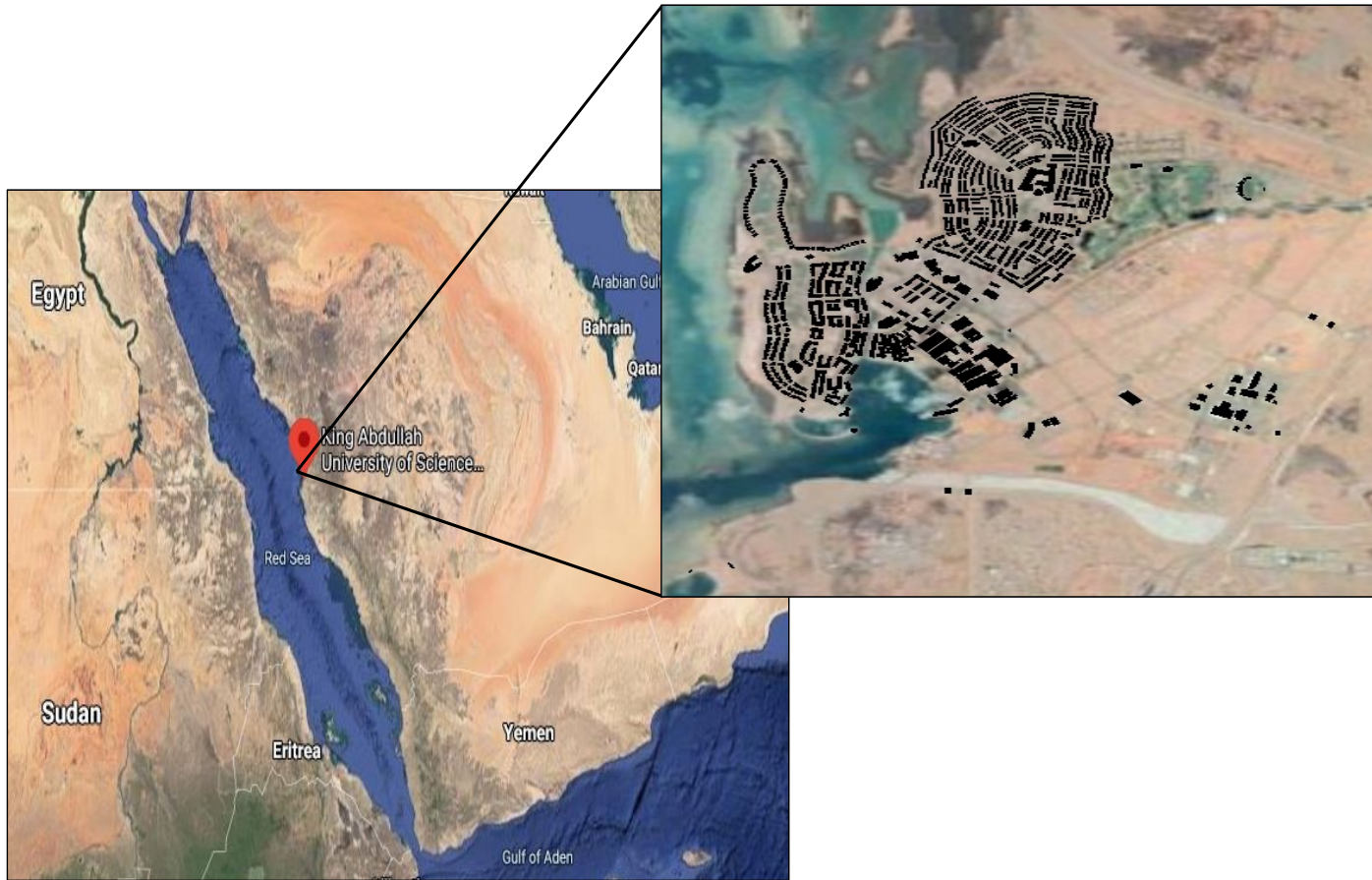
Exponential likelihood



$$W_2(f_0, f_m) = \min_{T^* \in \mathcal{T}(f_0, f_1)} \mathcal{L}(u, v) f_0(u)$$

- f_0 and f_m : observed and modeled concentration fields, respectively.
- \mathcal{T} : set of regular bijections mapping f_0 to f_m .
- $\mathcal{L}(u, v)$: Euclidean distance from point u to point $v = T(u)$.

Case Study: KAUST Synthetic Scenario



Results and Challenges

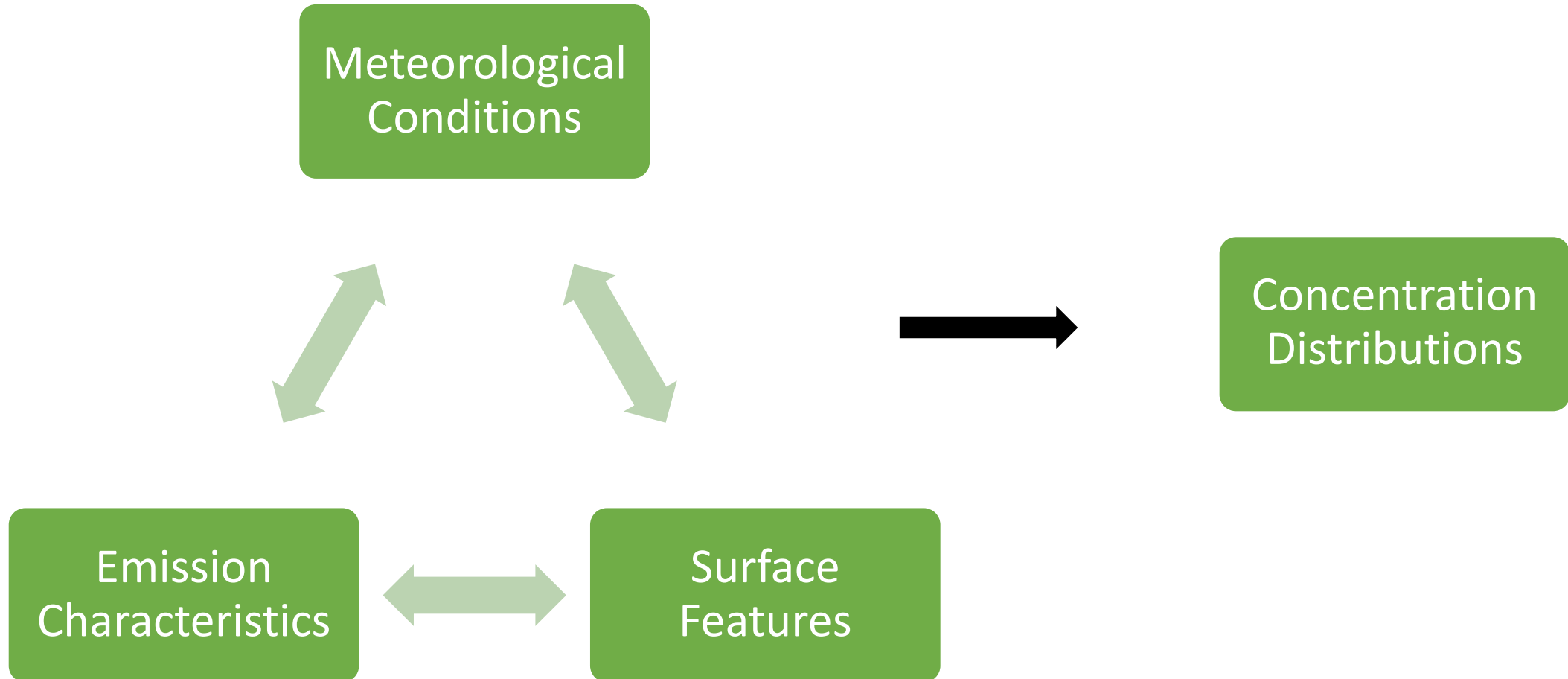
- Excellent solutions are obtained with the global W_2 dissimilarity metric.
- Challenge:
 - Each chain generation with **10,000** samples requires **143** hours.
 - Numerous runs of the expensive physical dispersion model.
 - High Cost of the W_2 Distance: Half of the computational time is spent to calculate the W_2 distance for each sample.

Solution: Use DL

- The acceleration of tradition Bayesian inference by training a NN to predict air pollutant concentrations based on given flow conditions and emission characteristics.
- Coupling this emulator with a NN approximation of the likelihood distribution to synergistically accelerate computations.
- Full operation on GPUs, leveraging parallel computing architectures to expedite computational costs.

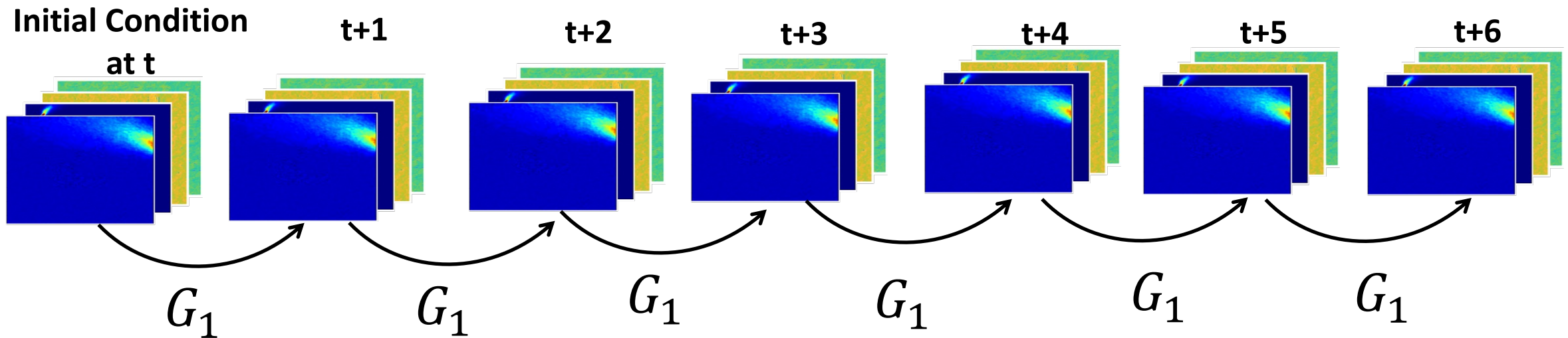


The Lagrangian Transport Surrogate Model: Learning Task

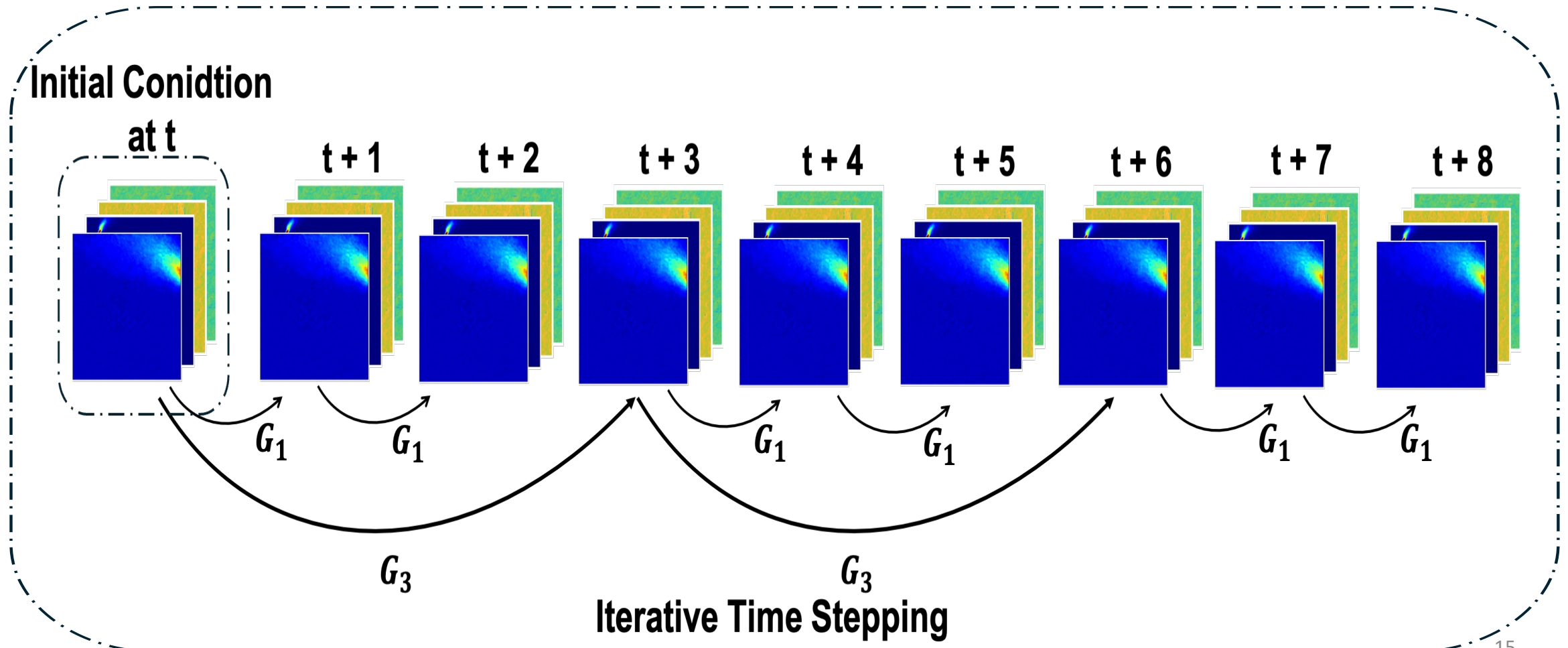


The Lagrangian Transport Surrogate Model: Training

- Prediction in time at each time step.
- Cumulative error growth for each time step.

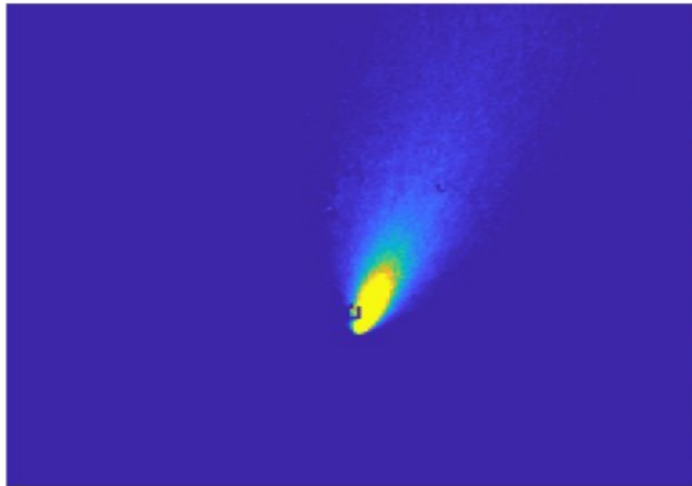


The Lagrangian Transport Surrogate Model: Training

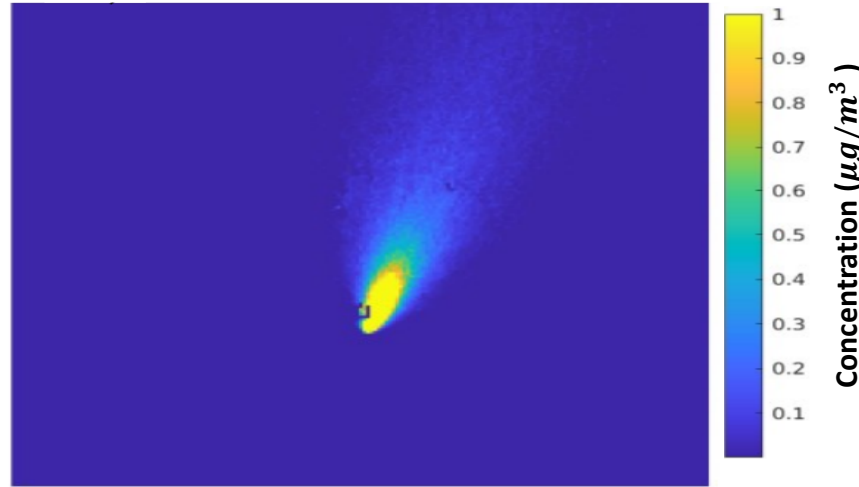


Examples of Predictions

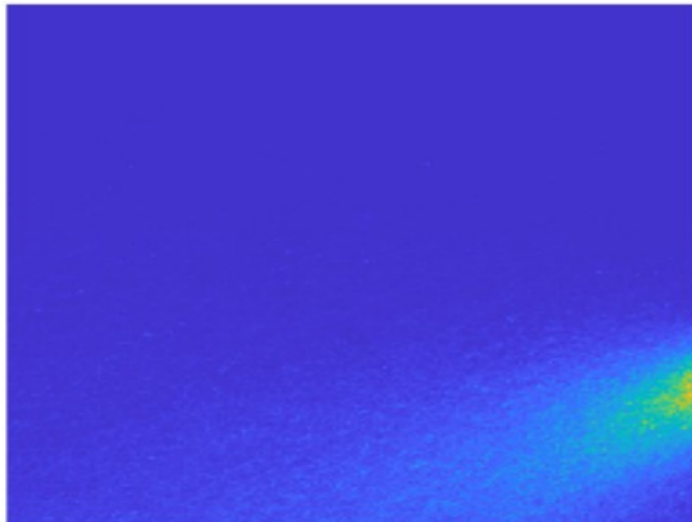
True C label at t+7



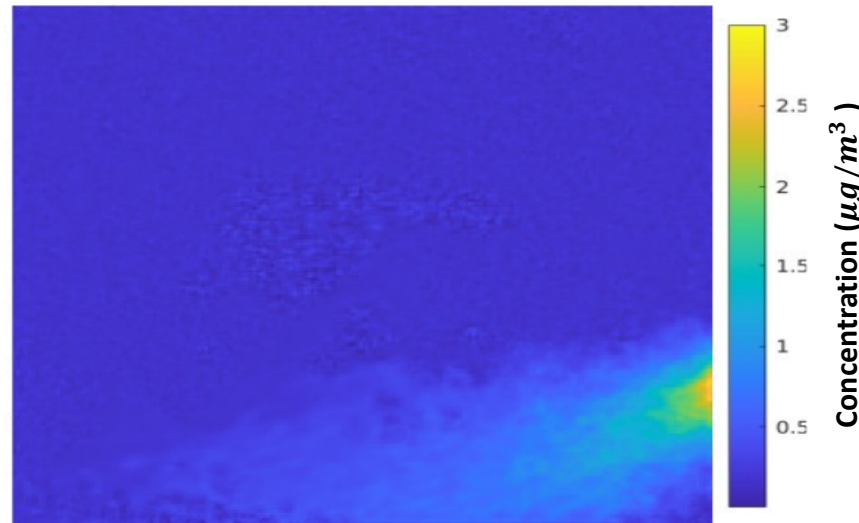
Predicted C at t+7



True C label at t+8



Predicted C at t+8

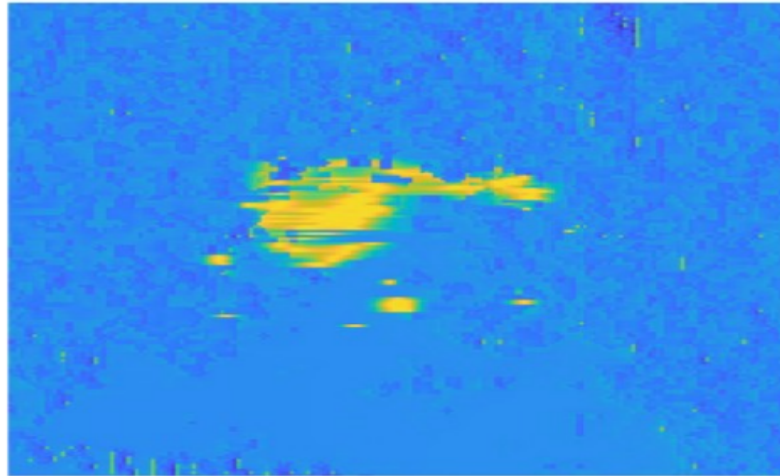


Evaluation Results:

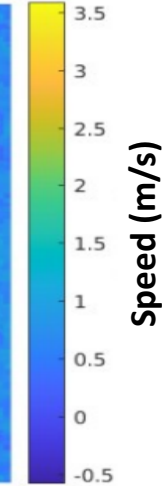
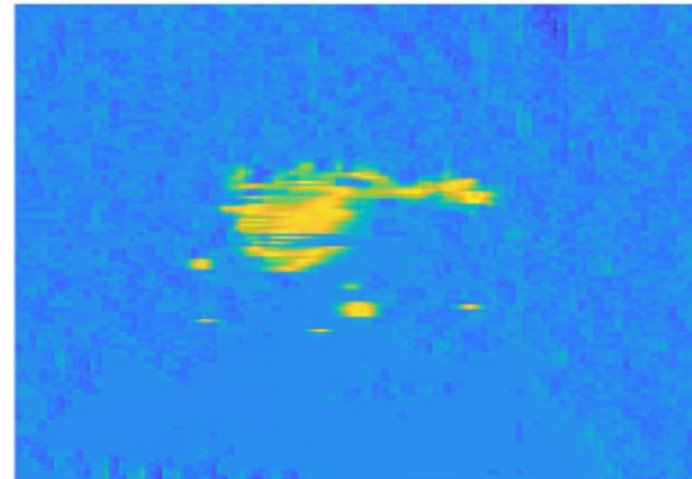
- RRMSE = 3.6%
- MBE = 0.015
- IOA = 98%

Examples of Predictions

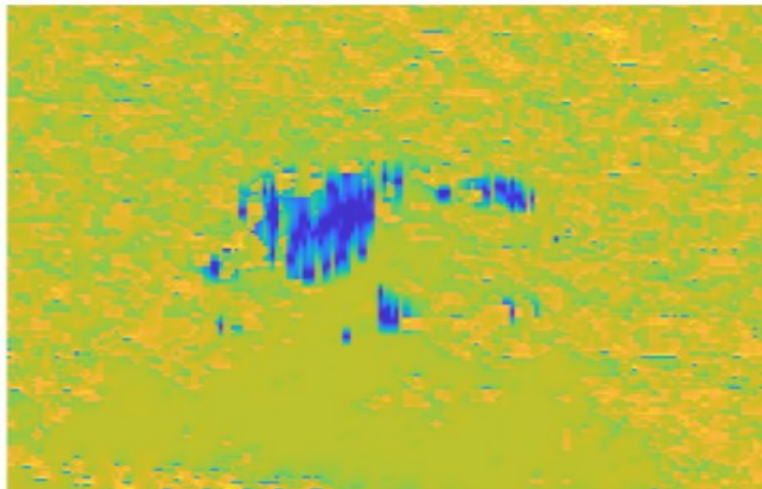
True u_f label at t+8



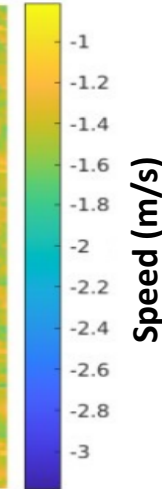
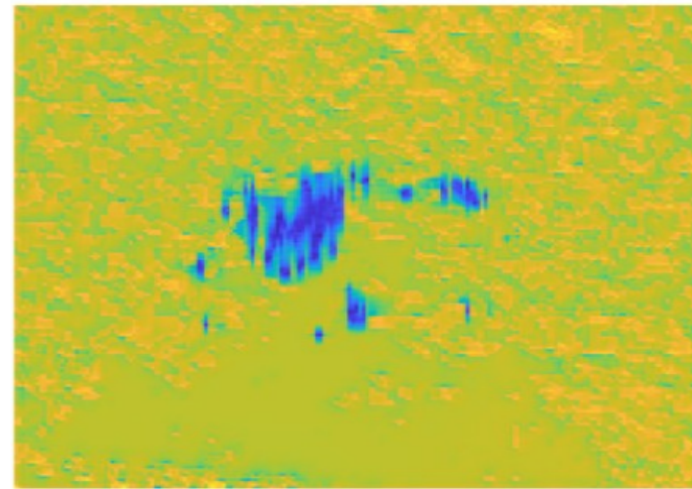
Predicted u_f at t+8



True v_f label at t+8



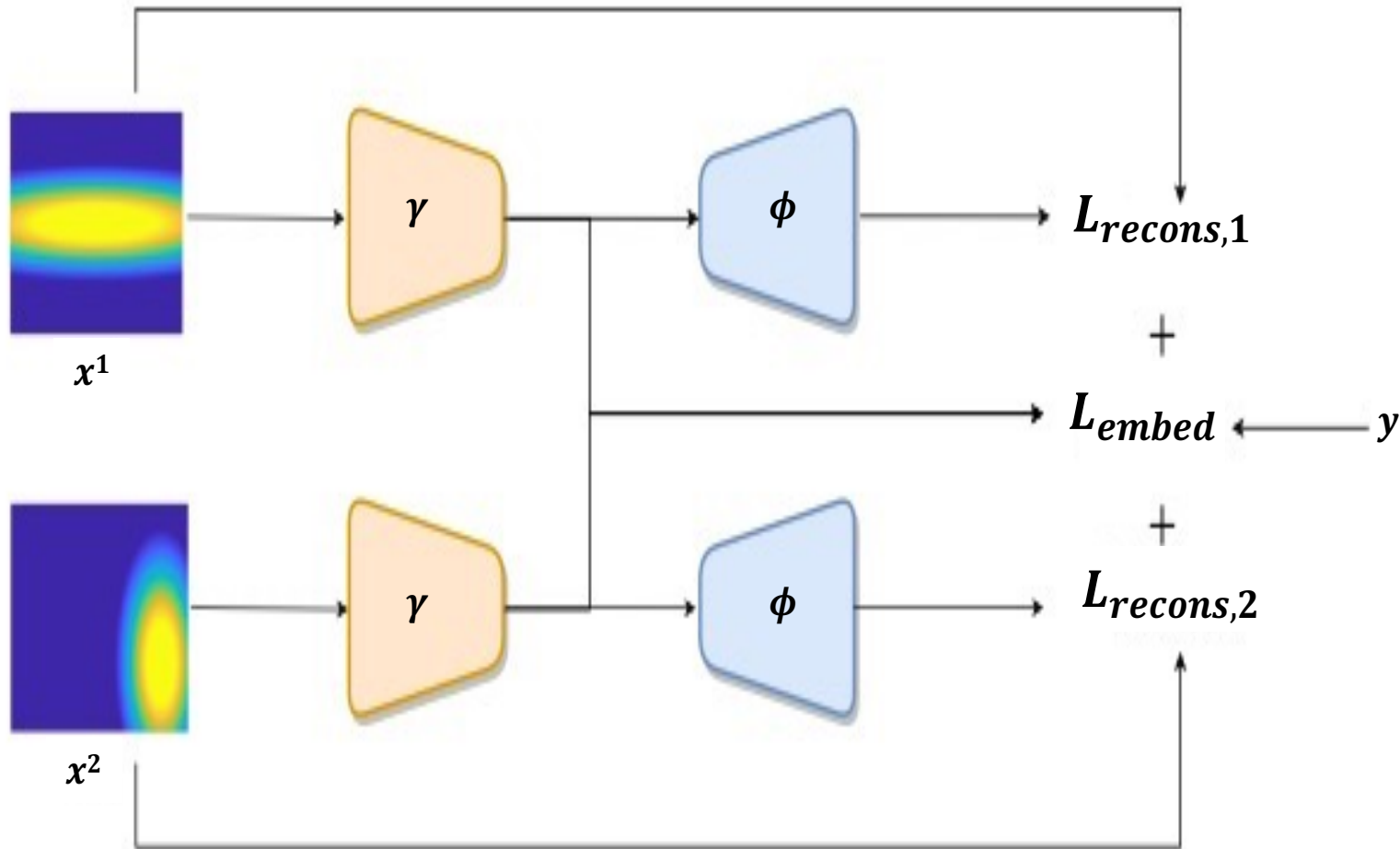
Predicted v_f at t+8



Evaluation Results:

- RRMSE = 3.6%
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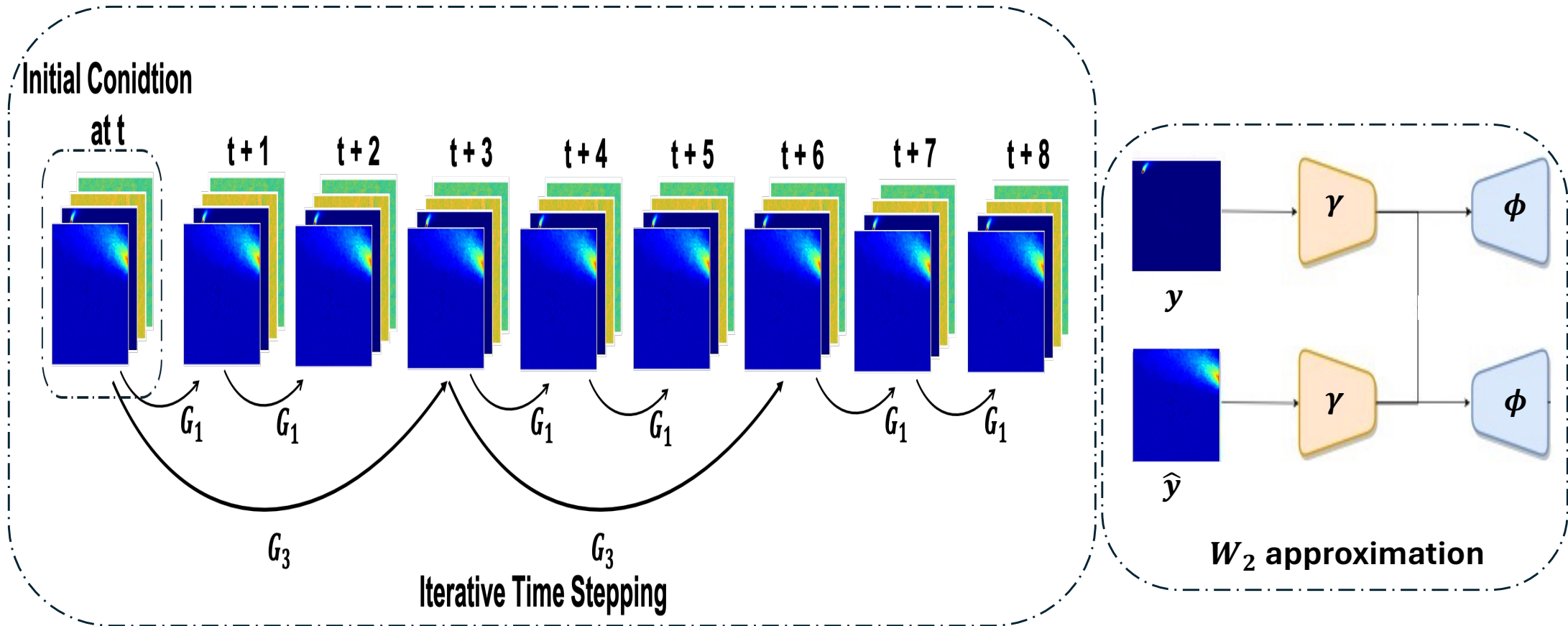
Siamese Network for W_2 Approximation



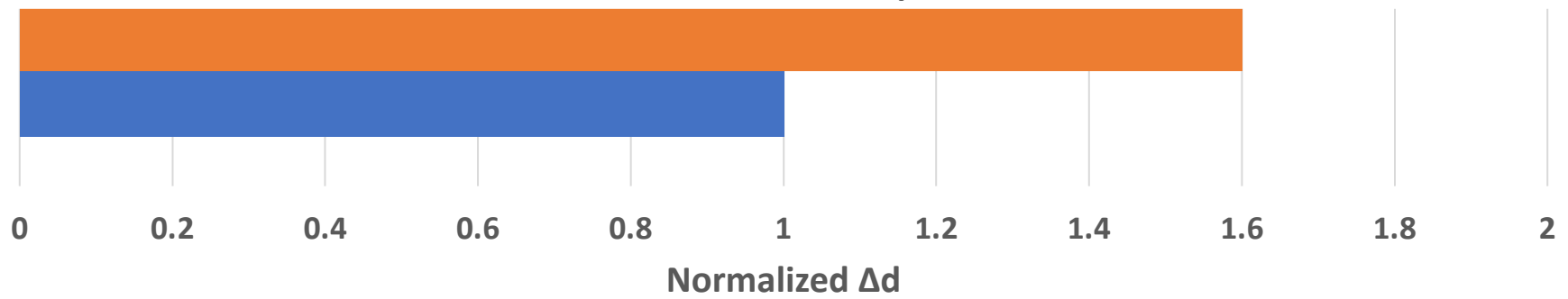
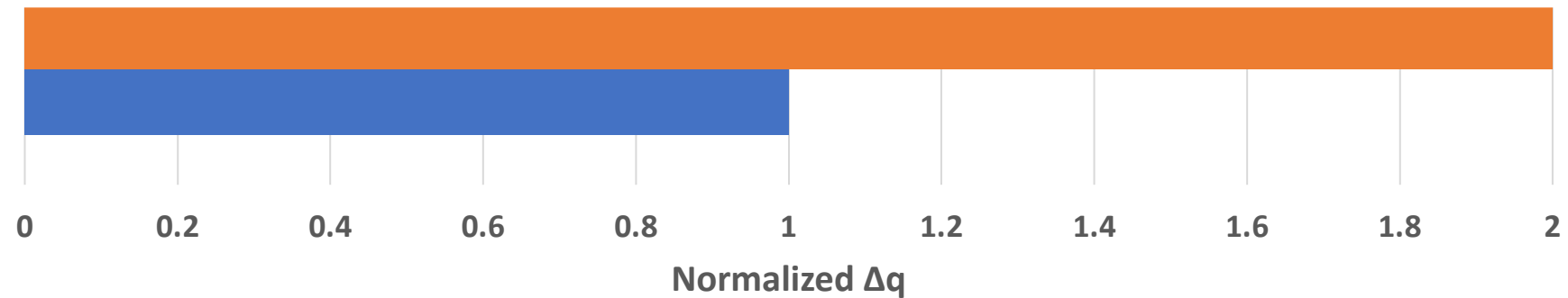
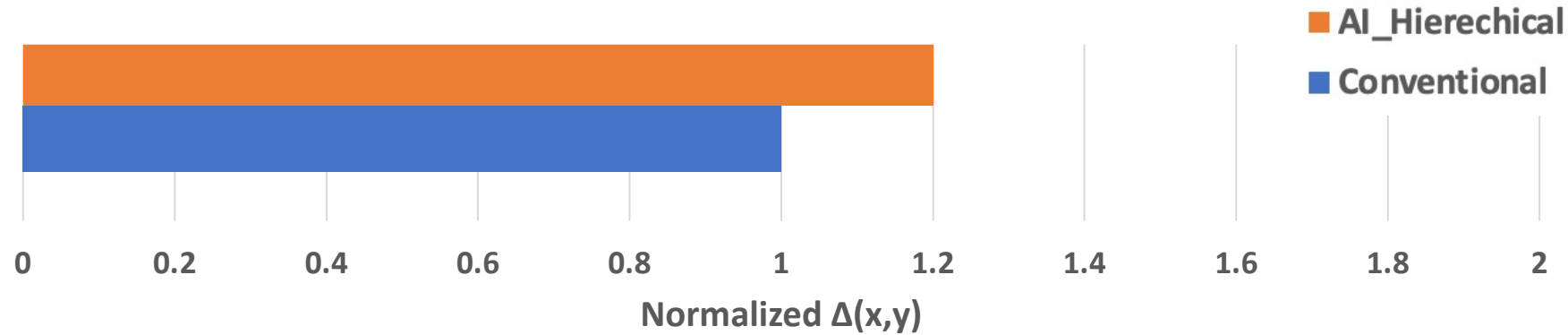
- x^1, x^2 : two input fields.
- γ : encoder.
- ϕ : decoder.
- y : the corresponding W_2 distance.
- $L_{recons,1}$ and $L_{recons,2}$: reconstruction loss terms of each input as computed by the KL divergence.
- L_{embed} : L_2 norm of the difference between the Euclidean distance of the embedded features and y .

Normalized L_2 error = 4.35%

The Dual Hierarchy



Bayesian Solution-10,000 samples



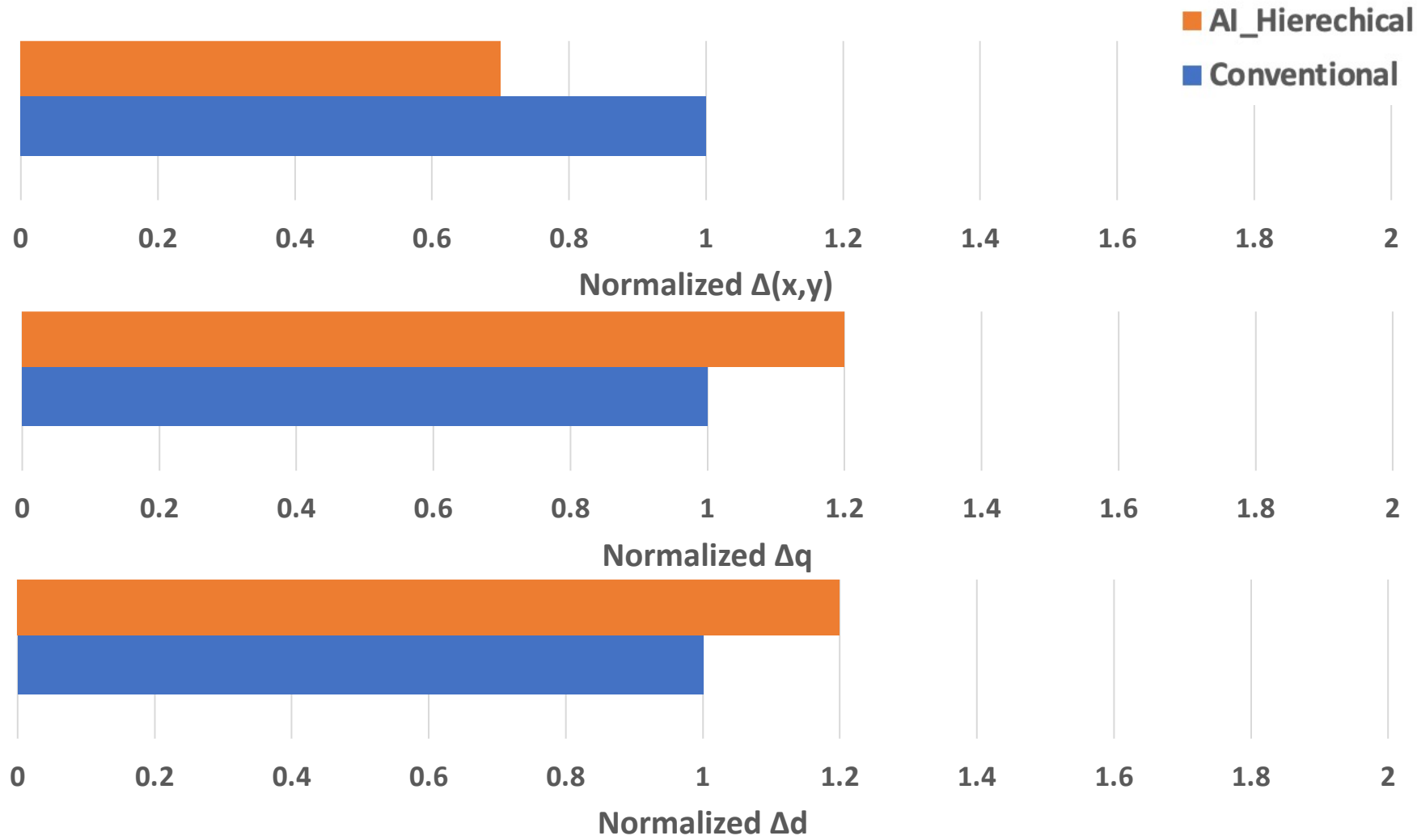
Computational Time

- Conventional: 6days!
- AI-Hierechical: 20minutes



More samples!

Bayesian Solution-100,000 samples



Computational Time

- Conventional: 60days!
- AI-Hierechical: 3.34hours



High Computational Savings
Better Convergence
Higher Confidence

Conclusion

- Successfully developed a NN surrogate model for Lagrangian dispersion, and a NN approximation for the likelihood estimation.
- Bayesian inference framework employs the dual NNs to infer the emission parameters in an urban environment.
- Suggested solutions results in appreciable reduction in computational requirements with minimal loss in performance.
- Our approach can accurately identify sources of air pollution, thus help in responding to harmful emissions and improve overall air quality.





Thank you for your time and attention!

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